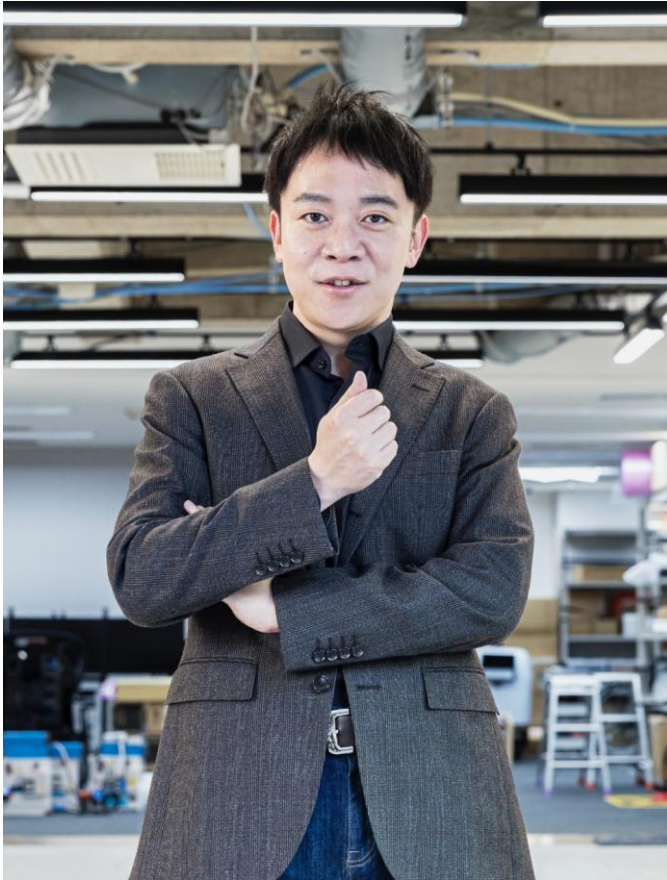


# AI for Autonomous Driving

Shinpei Kato

Chairman, The Autware Foundation





## Shinpei Kato

An internationally renowned expert in computer science, and a pioneer in the evolution of open-source software for autonomous driving technology.

**2023 – Present.** CEO of TIER IV; Specially Appointed Professor, The University of Tokyo.

**2018 – Present.** Chairman of The Autoware Foundation.

**2016 – 2023.** Full-Time Associate Professor in Computer Science, The University of Tokyo.

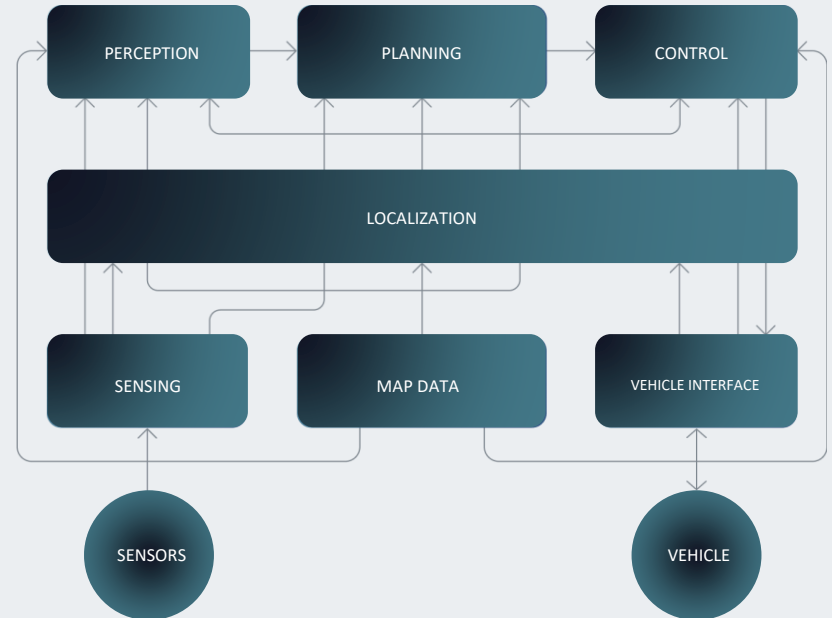
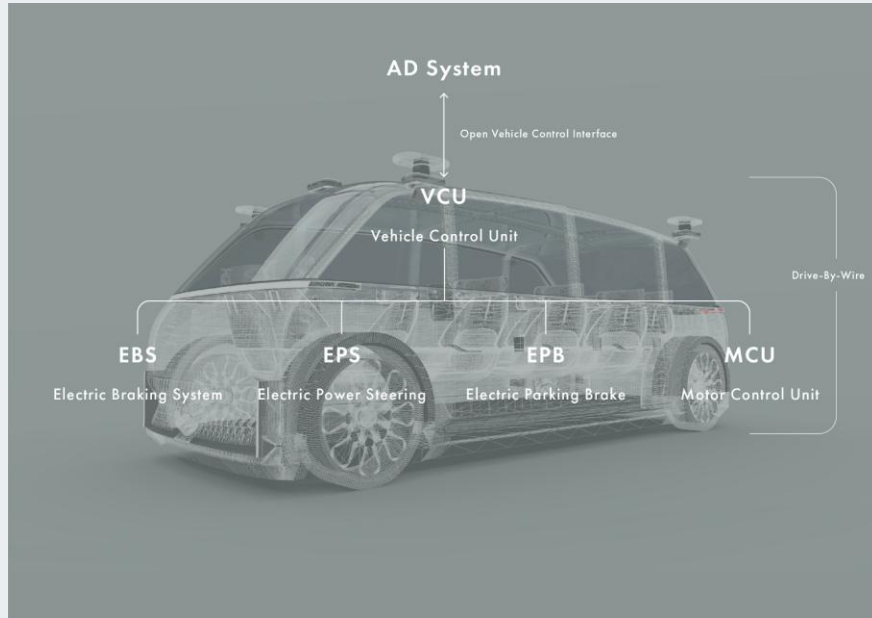
**2012 – 2016.** Full-Time Associate Professor in Information Science, Nagoya University.

**2009 – 2012.** Postdoc Researcher, Carnegie Mellon University & University of California, Santa Cruz.

**2008.** Received Ph.D. in Engineering, Keio University.

**1982.** Born.

# Autonomous Driving (AD)



# Open Source and Business Strategy

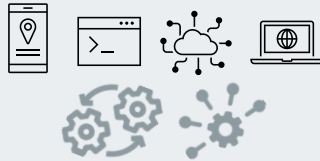
The Summit



**Customer Deal**

TIER IV provides solutions.

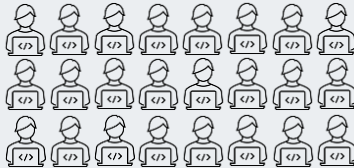
9-th Station



**Product**

TIER IV develops a platform.

5-th Station



**Open Source**

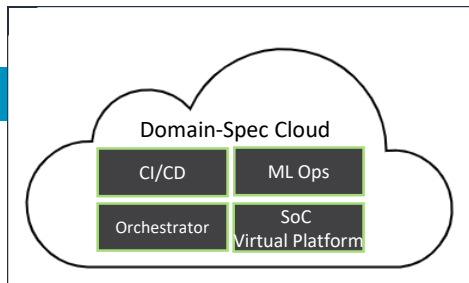
TIER IV leads Autware.



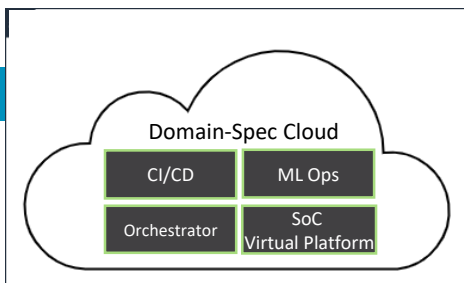


# Software-Defined Vehicles Architecture

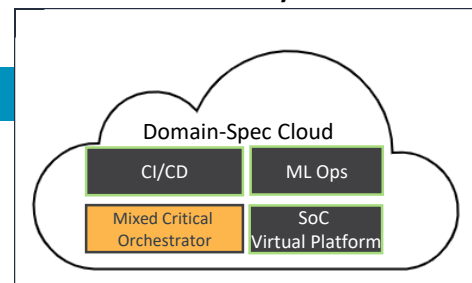
### Monolithic Domain-Spec Stack



### Microservices Based Domain-Spec Stack

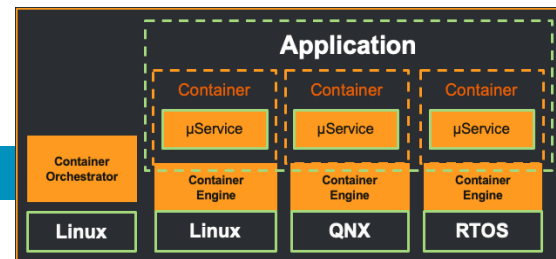
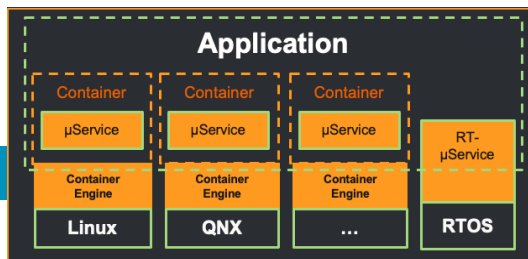
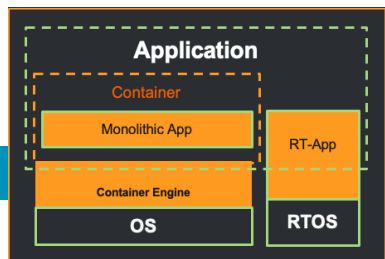


### Microservices Based Domain-Spec Stack With Mixed Criticality Orchestrator

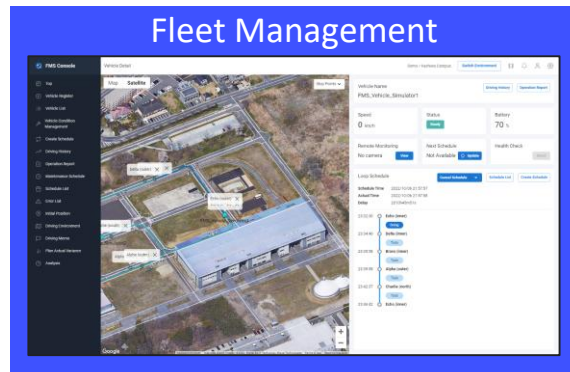
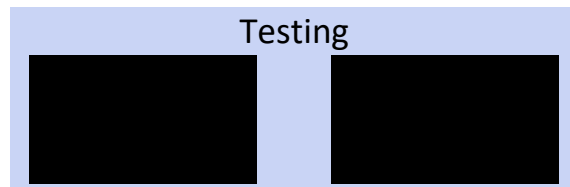
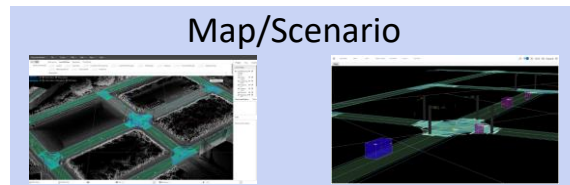
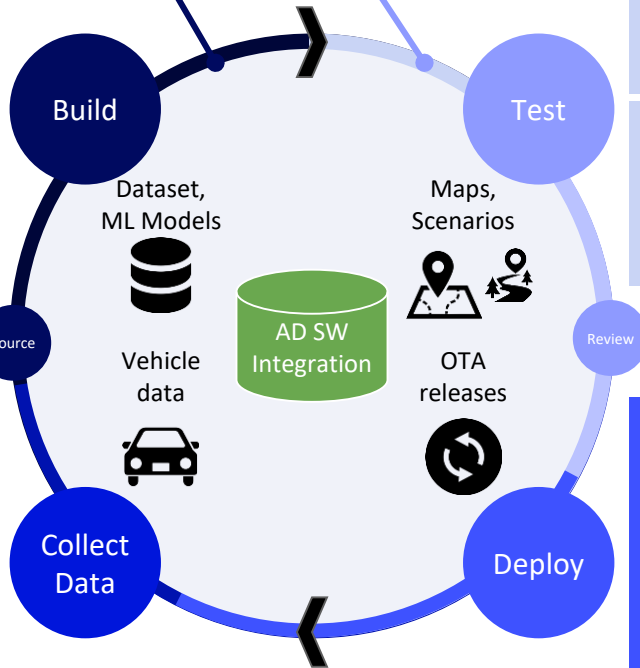
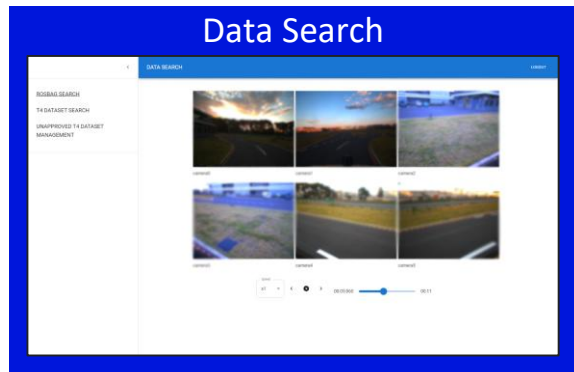
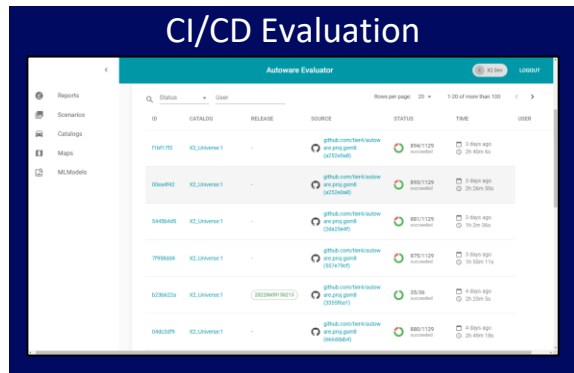


## Cloud-Native Development

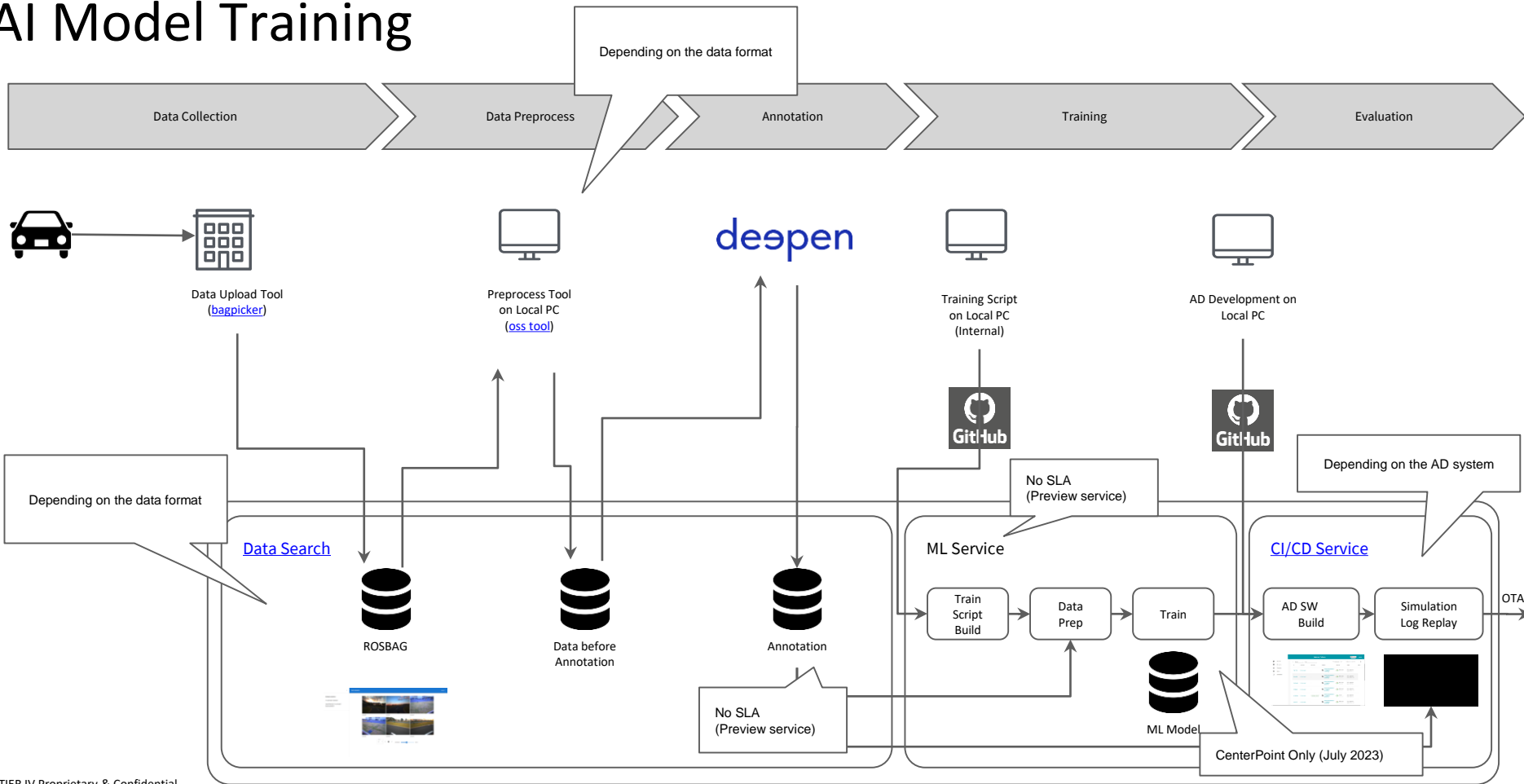
- DevOps / MLOps
- Continuous Delivery
- Microservices
- Containers for parity
- Environmental parity



# DevOps Framework



# AI Model Training



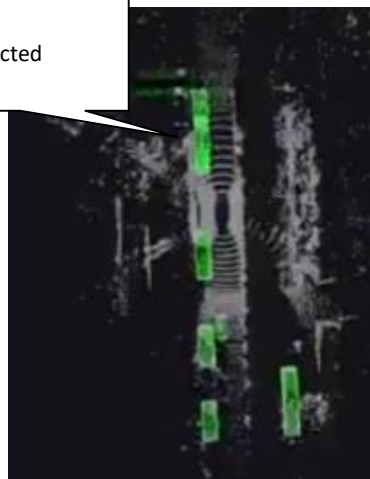
# Domain Adaptation Challenges

NOT detected...

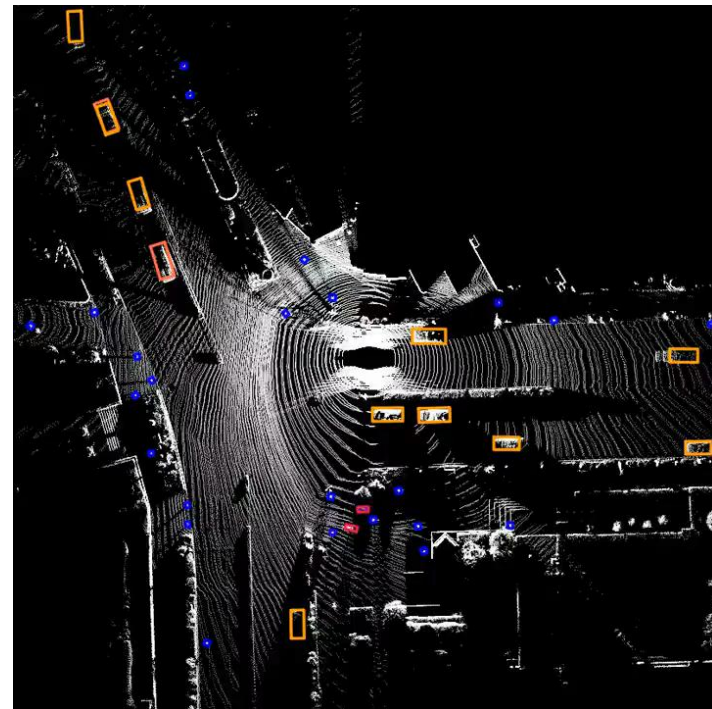


Without domain adaptation

Detected



With domain adaptation

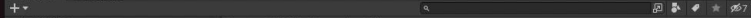
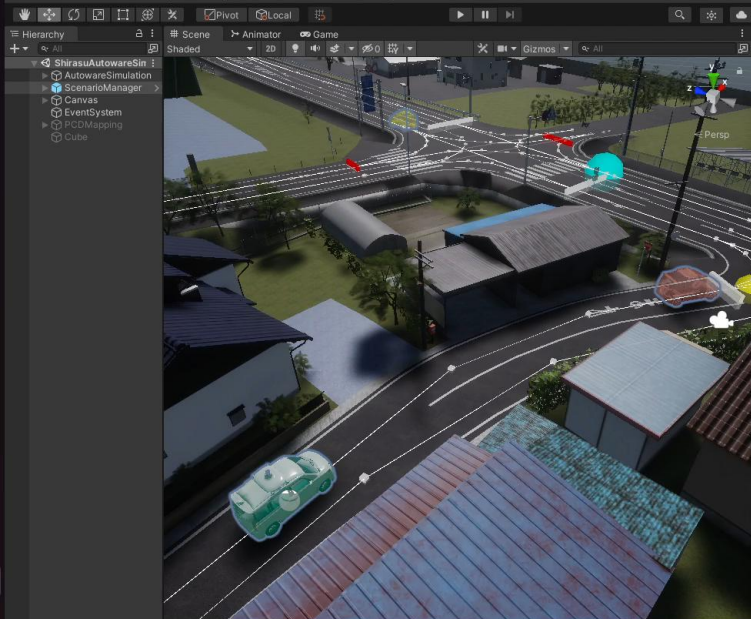


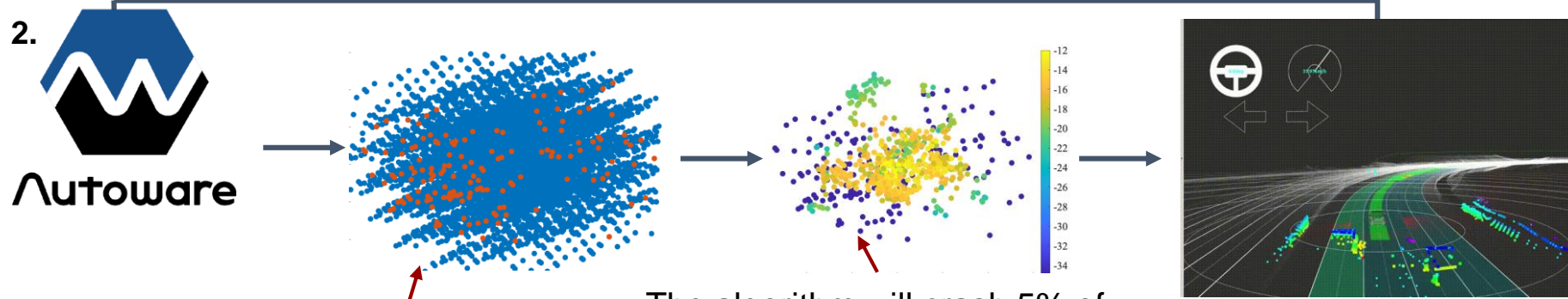
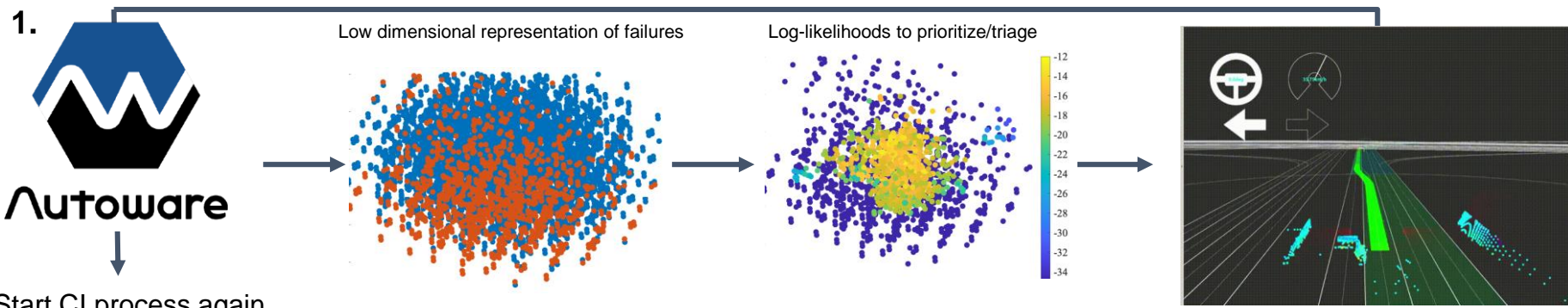


21-89

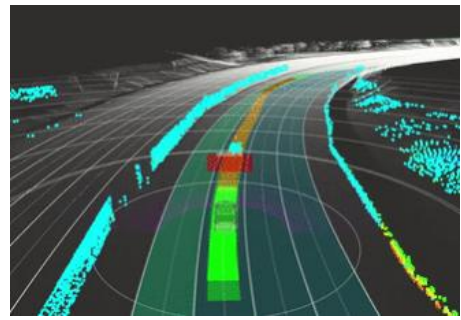
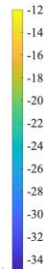
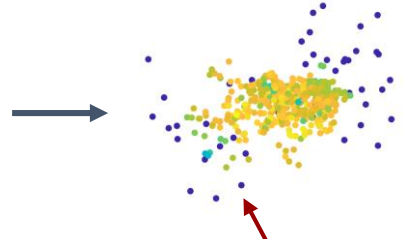
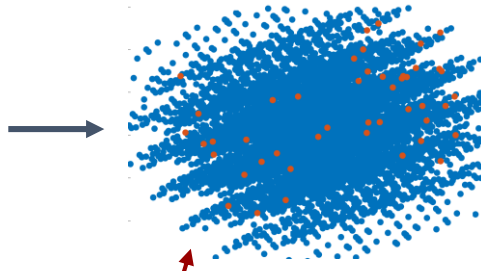
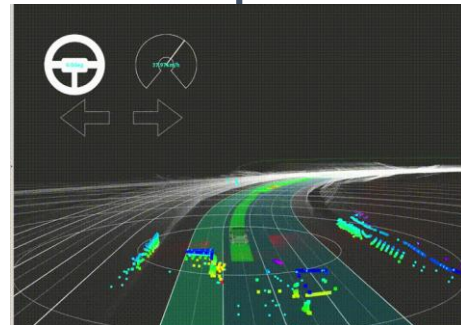
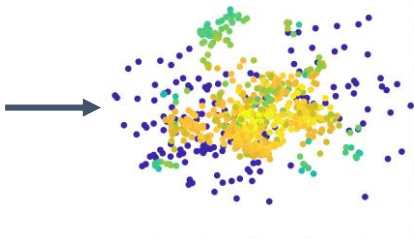
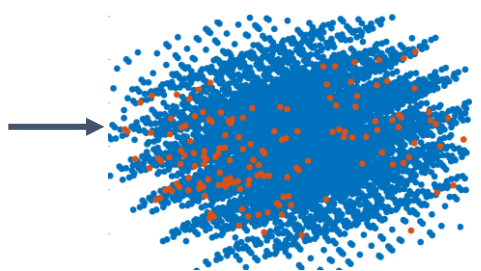


# Synthetic Data Generation with





⋮



0.52% of grid-search test points fail

The algorithm will crash 2.7% of the time on this scenario. Lane changes are successful 60.1% of the time

# Process Flow to Obtain L4 Operation Permit

## Authorized L4 Organization

- Operation Plan
- T&C Compliances
- Training to operators

Authorized L4 Operator

- Status monitoring
- In case of incident;
  - Reporting Police/ Fire department
  - Send personals to incident site for assistances

① Operation Plan Submission

③ Approval

*Administrative disposition when violates the law*

Remote Monitoring (or safety Operator in vehicle)



PPSC\*



② Hearing

Local Gov.



Mayor



Operational Design Domain (ODD)

\*都道府県公安委員(PPSC): Prefectural Public Safety Commissioner



# TIER IV

THE ART OF  
OPEN SOURCE,  
REIMAGINE  
INTELLIGENT  
VEHICLES.

THANKS !